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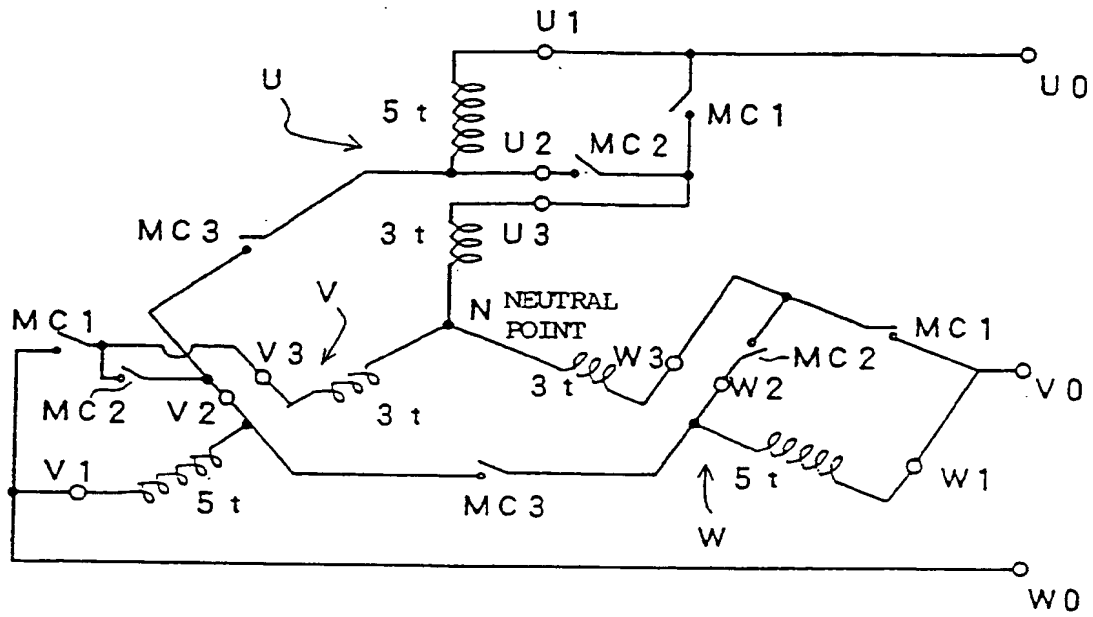
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(54) **METHOD AND APPARATUS FOR CONTROLLING AND DRIVING INDUCTION MOTOR.**

(57) A method and apparatus for controlling and driving an induction motor, by which its constant output power can be generated in a wide rotating range. Each of the star-connected windings of the induction motor is divided into two parts, (5t and 3t), at a predetermined ratio of their numbers of turns (e.g. 5:3). At a low speed, only changeover switches MC2 are closed, and through the divided windings (5t and 3t), currents flow. At a medium speed, only changeover switches MC3 are closed, and only through the divided windings (5t), currents flow. At a high speed, only changeover switches MC1 are closed, and only through the divided windings (3t), currents flow. That is, the induction motor is driven, by changing over the number of turns of each winding into one of three stages, so as to make it large at a low speed and make it small as the speed of the motor is increased.

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Fig. 2



TECHNICAL FIELD

The present invention relates to a controlling method and apparatus for actuating an induction motor, more particularly to an actuating control method for an induction motor suitably applied for controlling a main shaft of a machine tool, which requires a predetermined output in a wide speed region ranging from a low speed to a high speed.

BACKGROUND ART

A recent induction motor is designed so that a large torque can be obtained in a low speed region with the same primary current value by use of a switching control of primary windings and a slip control.

That is, in a conventional switching operation for the primary windings, there are provided two terminals so that primary windings of Y-Y connection of respective phases are supplied with exciting current from these two terminals. A first terminal is provided to fully supply exciting current to primary winding of each phase for rotation. While a second terminal is provided at an intermediate point of each primary winding so as to supply the exciting current to a part of each primary winding.

Then, the switching operation of the primary windings is carried out in such a manner that electric power is only supplied from the first terminal in the case where a rotational speed of the motor is low, so that each phase winding is fully supplied with exciting current. And, electric power is only supplied from the second terminal in the case where the rotational speed of the motor is high, so that each phase winding is partly supplied with exciting current.

In the case where the motor is controlled through the switching operation of the primary windings as is described above, there was a problem such that an undesirable drop of output occurs when the primary winding is switched from a low-speed winding to a high-speed winding or vice versa where the extent of a rotational speed region exceeds a certain limit, thereby causing a problem such that a constant output cannot be obtained throughout a wide speed region.

Fig. 4 is a graph showing an output characteristics of the motor in relation to its rotational speed, where the actuation of the motor is controlled on the basis of such a switching operation of the primary windings. As shown in Fig. 4, an output of the motor will not increase proportionally even when the rotational speed of the motor is increased to a relatively high speed range as far as the motor is actuated by the low-speed windings.

Thus, even when the winding is switched to the high-speed windings from the low-speed windings, an output necessary for obtaining a predetermined torque will not be generated as far as the rotational speed of the motor is within the relatively low-speed range of the speed region available by the high-speed windings. For this reason, there will occur an output reduction whose phenomenon is shown in Fig. 4 as area a filled with slant lines.

DISCLOSURE OF INVENTION

An object of the present invention is to provide a controlling method and apparatus for actuating an induction motor capable of preventing the occurrence of the above-described output reduction area.

The present invention provides a control apparatus for actuating an induction motor comprising: phase windings of Y-connection type each having one end connected to an electric power supply terminal and the other end connected to a neutral point; a first and a second split windings, which are formed by splitting each of said windings at a predetermined split ratio based on the number of turns of winding, and the split points of said split windings are respectively connected to a first and a second intermediate terminals; a first changeover switch interposed between said first intermediate terminal of each phase and said electric power supply terminal; a second changeover switch interposed between said first and second intermediate terminals of each phase; a third changeover switch interposed between said second intermediate terminals of said second split windings; and a switching control means for on-off controlling said first, second and third switches in accordance with a rotational speed of said induction motor.

Furthermore, according to the present invention, in controlling the actuation of the induction motor with above-described apparatus, when the rotational speed of the motor is in a low speed region, only the second changeover switch is turned on to increase a number of turns of each phase winding to its maximum value so that a large torque can be generated even in the low speed region. On the other hand, in the case where the rotational speed of the motor is in a middle speed region, only either the first or the third changeover switch is turned on to exclusively supply exciting current to the split winding having a larger number of turns so that a large torque can be generated in the middle speed region too.

Still further, in the case where the rotational speed of the motor is in a high speed region, only whichever unused of either the first or the third changeover switch is turned on to exclusively supply exciting current to the unused split winding having a smaller number of turns so that a large torque can similarly be generated in the high speed region.

#### BRIEF DESCRIPTION OF DRAWINGS

Fig. 1 is a block diagram showing an actuation control system for induction motor in accordance with one embodiment of the present invention;

Fig. 2 is an explanatory view showing how respective phase windings of the induction motor, terminals, changeover switches of the switching circuit 6 are connected to each other;

Fig. 3 is a flow chart showing a processing for controlling the induction motor to be executed on the processor equipped in the control circuit in accordance with this embodiment;

Fig. 4 is a graph showing an output characteristics in relation to a rotational speed of the motor, whose actuation is controlled on the basis of a conventional switching operation of the windings.

#### BEST MODE FOR CARRYING OUT THE INVENTION

In Fig. 1, three phase windings U, V and W of an induction motor 1 are connected to constitute a Y-Y connection. As will be described later, three winding terminals U1, V1 and W1, and six intermediate terminals U2, U3, V2, V3, W2 and W3 are provided in these phase windings U, V and W, respectively.

These terminals are connected to a switching circuit 6 contained in a motor controller 3. This switching circuit 6 includes three change-over switches MC1 to MC3 (refer to Fig. 2) respectively for each of three phases. These changeover switches may be either electromagnetic contactors or a TRIAC's (triode AC switch as a non-contact switch). A power circuit 5 is constituted of components such as a transistor inverter and the like, and supplies electric power through the switching circuit 6 to respective phase windings of the induction motor 1.

A control circuit 7 includes a processor (CPU), memory means such as ROM, RAM, an LSI, an A/D converter etc. in order to control the power circuit 5. A rotational speed sensor 2 detects a rotational speed of the induction motor 1. The control circuit 7 further controls the motor 1 by selectively turning on three changeover switches MC1 to MC3 provided in the switching circuit 6 in accordance with the rotational speed detected through the rotational speed sensor 2. A three-phase AC electric power source 4 supplies electric power to the motor controller 3.

Above-described induction motor actuation control system differs from a conventional induction motor actuating system in that each phase winding in the motor 1 is equipped with three terminals unlike the conventional induction motor actuation control system which is provided with only two terminals, and further in that the former system carries out a switching operation with respect to above-described three terminals, while the conventional system carries out a switching operation with respect to only two terminals.

Next, with reference to Fig. 2, how respective phase windings of the induction motor 1, terminals, changeover switches of the switching circuit 6 are connected to each other will be explained in detail.

Respective phase windings of U, V and W phases are connected to each other to constitute a Y-Y connection. Each of these three phase windings of U, V and W phases is divided into two split windings 3t and 5t having a split ratio of 3 : 5. Namely, one split winding whose number of turns is smaller is designated by the reference numeral 3t, and the other split winding whose number of turns is larger is designated by the reference numeral 5t.

One ends of respective split windings 3t are connected together to a neutral point N, and the other ends of these split windings 3t are connected to the intermediate terminals U3, V3 and W3, respectively, so as to be led out of the motor 1.

On the other hand, the split points of the split windings 5t are connected to the intermediate terminals U2, V2 and W2, respectively to be led out of the motor 1. Furthermore, winding terminals U1, V1 and W1 are directly connected to the terminals U0, V0 and W0 to which the power circuit 5 supplies electric power.

The intermediate terminals U3, V3 and W3 are connected to these electric power supply terminals U0, V0 and W0 via the contact points of changeover switches MC1 provided in the switching circuit 6, respectively. The intermediate terminals U2, V2 and W2 are connected to the intermediate terminals U3, V3 and W3 via the contact points of changeover switches MC2, respectively. Furthermore, the intermediate terminals U2, V2 and W2 are connected to each other via the contact points of changeover switches MC3.

As respective phase windings of the induction motor 1 are disposed and connected to respective switches as described above, when only the changeover switches MC1 are turned on, while other

changeover switches MC2 and MC3 are turned off, electric power is supplied from the electric power supply terminals U0, V0 and W0 to the intermediate terminals U3, V3 and W3 via the contact points of the changeover switches MC1 so as to exclusively activate the split windings 3t of U, V and W phases.

On the other hand, when only the changeover switches MC2 are turned on, while other changeover switches MC1 and MC3 are turned off, electric power is supplied to winding terminals U1, V1 and W1, and the split windings 5t and 3t of respective phases, or all the windings of respective phases, will be activated.

Furthermore, when only the changeover switches MC3 are turned on, while other changeover switches MC1 and MC2 are turned off, respective intermediate terminals U2, V2 and W2 are connected to each other through the contacts of the changeover switches MC3. Thus, this connecting point becomes a neutral point, and electric power is supplied from winding terminals U1, V1 and W1, and therefore only the split windings 5t of respective phases are exclusively activated.

Accordingly, the rotational speed region of the induction motor 1 is divided into three regions of low speed, middle speed and high speed so that above-described changeover switches MC1, MC2 and MC3 can be on-off controlled in these three regions in accordance with the following table.

TABLE 1

Changeover switch	MC1	MC2	MC3
low speed region	off	on	off
middle speed region	off	off	on
high speed region	on	off	off

Then, Fig. 3 is a flow chart showing a processing for controlling the induction motor to be executed on the processor equipped in the control circuit 7 of the controller 3. The processor executes this processing for a predetermined period.

First of all, various parameters necessary for controlling the motor in respective speed regions of low speed, middle speed, and high speed are stored in the memory equipped in the control circuit. More specifically, current gain to be used in current loop processing, slip gain to be used in slip control, voltage gain to be used in voltage control and rotational speed gain to be used in speed control are set and stored in the memory.

Then, when electric power source is turned on to actuate the induction motor, in step S1, the processor in the control circuit 7 will judge whether or not the rotational speed detected by the rotational speed sensor 2 is equal to or less than a speed value preset as a switching threshold speed from the low speed region to the middle speed region.

If the rotational speed of the motor 1 is in the low speed region, in step S2, the processor outputs a signal to turn on the changeover switch MC2 and turn off the changeover switches MC1 and MC3 respectively contained in the switching circuit 6 to cause the changeover switches MC2 to be turned on, and the changeover switches MC1 and MC3 to be turned off, respectively.

As a result, all the split windings 5t and 3t of U, V and W phases are supplied with exciting current. Therefore, a sufficiently large torque can be obtained in this low speed region. Subsequently, in step S3, the processor reads in various low speed parameters stored in the memory.

Next, the processor proceeds to step S9 to control the power circuit 5 on the basis of these low speed parameters in the same manner as the conventional system to actuate the induction motor.

As is described above, in the case where the rotational speed detected by the rotational speed sensor 2 installed in the motor 1 is in the low speed region, the processor repeatedly execute each processing defined by the steps S1, S2, S3 and S9 in the succeeding processing periods.

On the other hand, if it is detected that the rotational speed of the motor 1 is in a middle speed region defined by the above-described speed value being set as the switching threshold speed from the low speed region to the middle speed region and another speed value being set as the switching threshold speed from the middle speed region to the high speed region in a step S4, the processor outputs a signal to turn on the changeover switches MC3 and turn off the changeover switches MC1 and MC2 so that only the split windings 5t of U, V and W phases are exclusively supplied with exciting current for excitation. Thereafter, in step S6, the processor reads in various middle speed parameters stored in the memory to control the power circuit 5 in actuating the induction motor 1.

In this case, as the substantial number of turns actually excited in each phase winding becomes smaller than that in the case of the actuation in the low speed region, the induction motor can generate a large

torque even in a higher speed region compared with the case of the actuation in the low speed region.

Furthermore, if the rotational speed detected by the rotational sensor 2 is equal to or larger than the speed value defined as the threshold speed from the middle speed to the high speed (i.e. if it is judged that the rotational speed is neither in the low speed region nor in the middle speed region), the processor proceeds to step S7 to turn on the changeover switches MC1 and turn off the changeover switches MC2 and MC3.

Then, in step S8, the processor reads in various high speed parameters stored in the memory and controls the power circuit 5 to actuate the induction motor 1 according to these high speed parameters.

In this case, only the changeover switches MC1 are turned on, so that the split windings 3t of respective phases are exclusively supplied with exciting current. Thus, the induction motor will become able to generate a large torque in this high speed region.

Further, according to the above embodiment, though the number of turns of the split winding connected to the neutral point is made smaller than the number of turns of the split winding connected to the winding terminal; however, this arrangement may be reversed.

In such a case, however, only the changeover switch MC1 is turned on in the middle speed region, and only the changeover switch MC3 is turned on in the high speed region.

Moreover, according to the above-described embodiment, each phase winding is divided into two at a predetermined ratio; however, the phase winding can be divided into more than two so that the number of turns of winding to be supplied with the current can be selected according to the rotational speed of the induction motor.

However, as disclosed in the above-described embodiment, even if the winding is divided into only two, a constant output can be obtained in a speed region ranging wide enough.

According to the present invention, each phase winding is divided into two split windings having a predetermined split ratio; each split winding is selectively supplied with exciting current through the switching operation of changeover switches in response to the rotational speed of the induction motor; three different numbers of turns can be selected with respect to each phase winding so that relatively large number of turns can be used for the rotation in the low speed region, while relatively small number of turns can be used for the rotation in the high speed region, whereby large torque can be obtained throughout the low speed region, middle speed region and high speed region; and, as a result, constant output can be obtained throughout a wide speed region.

## Claims

### 1. A control apparatus for actuating an induction motor comprising:

respective phase windings of Y-connection type each having one end connected to an electric power supply terminal and the other end connected to a neutral point;

a first and a second split windings, which are formed by splitting each of said windings at a predetermined split ratio based on the number of turns of winding, the split points of said split windings being respectively connected to a first and a second intermediate terminals;

a first changeover switch interposed between said first intermediate terminal of each phase and electric power supply terminal;

a second changeover switch interposed between said first and second intermediate terminals of each phase;

a third changeover switch interposed between intermediate terminals of said second split windings; and

a switching control means for on-off controlling said first, second and third switches in accordance with a rotational speed of said induction motor.

### 2. A control method for controlling an induction motor with an actuation control apparatus for the induction

motor comprising: phase windings of Y-connection type each having one end connected to an electric power supply terminal and the other end to a neutral point; a first and a second split windings, which are formed by splitting each of said windings at a predetermined split ratio based on the number of turns of winding, the split points of said windings being respectively connected to a first and second intermediate terminals; a first changeover switch interposed between said first intermediate terminal of each phase and said electric power supply terminal; a second changeover switch interposed between said first and second intermediate terminals of each phase; a third changeover switch interposed between said second intermediate terminals of said second split windings; and a switching control means for on-off controlling said first, second and third switches; wherein said controlling method

comprising steps of:

turning on said second changeover switch and turning off said first and third changeover switches in the case where a rotational speed of the induction motor is in a low speed region;

turning on said third changeover switch and turning off said first and second changeover switches in the case where the rotational speed of the induction motor is in a middle speed region; and

turning on said first changeover switch and turning off said second and third changeover switches in the case where the rotational speed of this induction motor is in a high speed region.

3. A control method for actuating an induction motor in accordance with claim 2, in which said second split winding has a larger number of turns than said first split winding.

4. A control method for controlling an induction motor with an actuation control apparatus for the induction motor comprising: phase windings of Y-connection type each having one end connected to an electric power supply terminal and the other end to a neutral point; a first and a second split windings, which are formed by splitting each of said windings at a predetermined split ratio based on the number of turns of winding, the split points of said windings being respectively connected to a first and second intermediate terminals; a first changeover switch interposed between said first intermediate terminal of each phase and said electric power supply terminal; a second changeover switch interposed between said first and second intermediate terminals of each phase; a third changeover switch interposed between said intermediate terminals of said second split windings; and a switching control means for on-off controlling said first, second and third switches; wherein said controlling method comprising steps of:

turning on said second changeover switch and turning off said first and third changeover switches in the case where a rotational speed of this induction motor is in a low speed region;

turning on said first changeover switch and turning off said second and third changeover switches in the case where the rotational speed of this induction motor is in a middle speed region; and

turning on said third changeover switch and turning off said first and second changeover switches in the case where the rotational speed of this induction motor is in a high speed region.

5. A control method for actuating an induction motor in accordance with claim 4, in which said first split winding has a larger number of turns than said second split winding.

Fig. 1

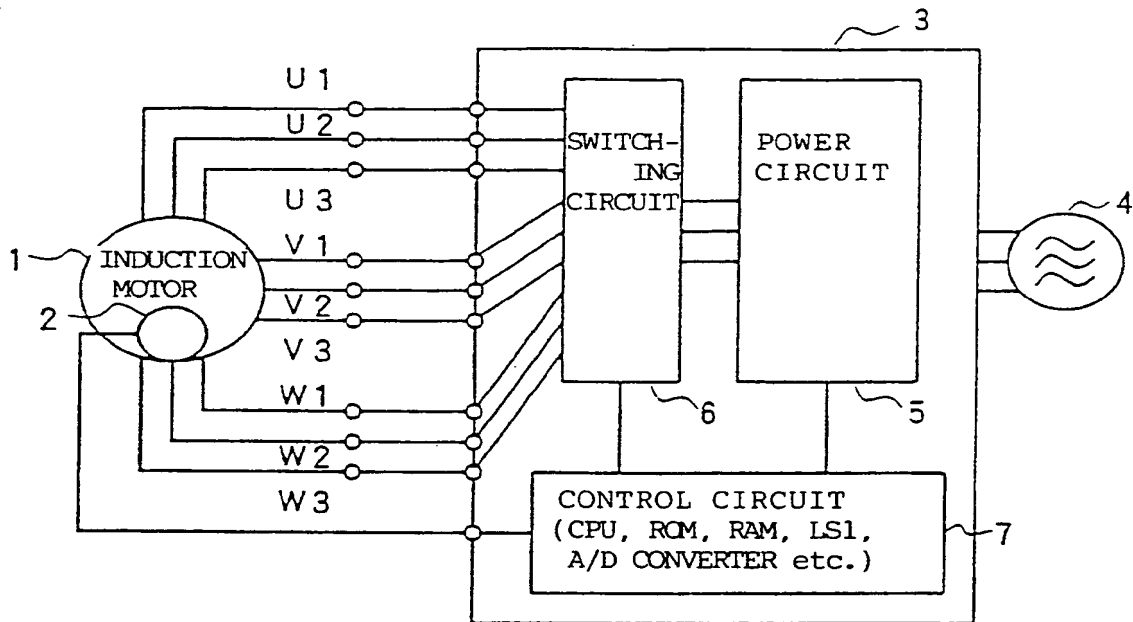


Fig. 2

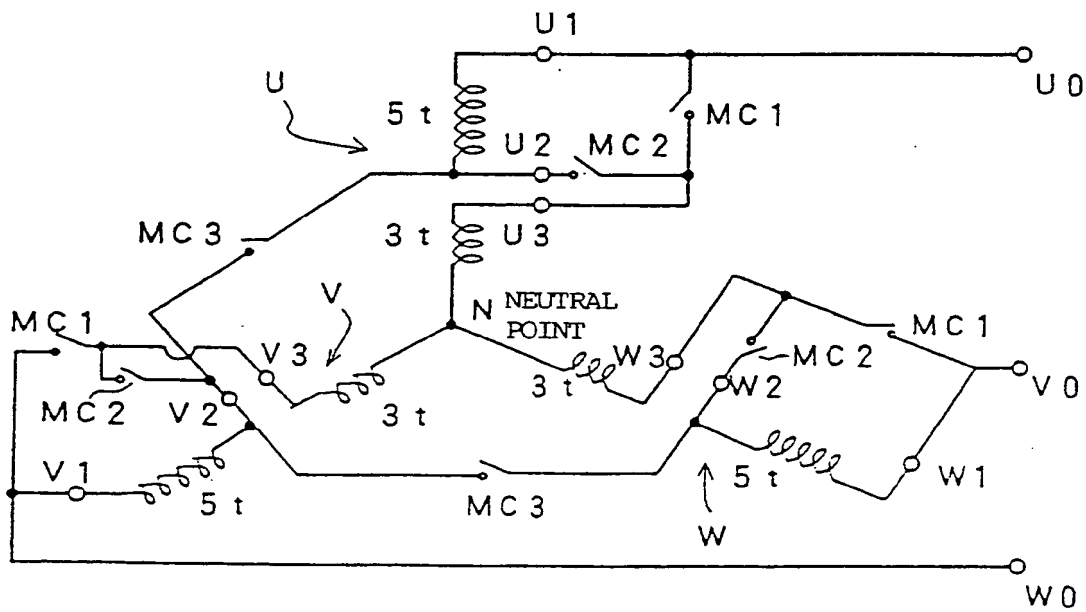




Fig. 3

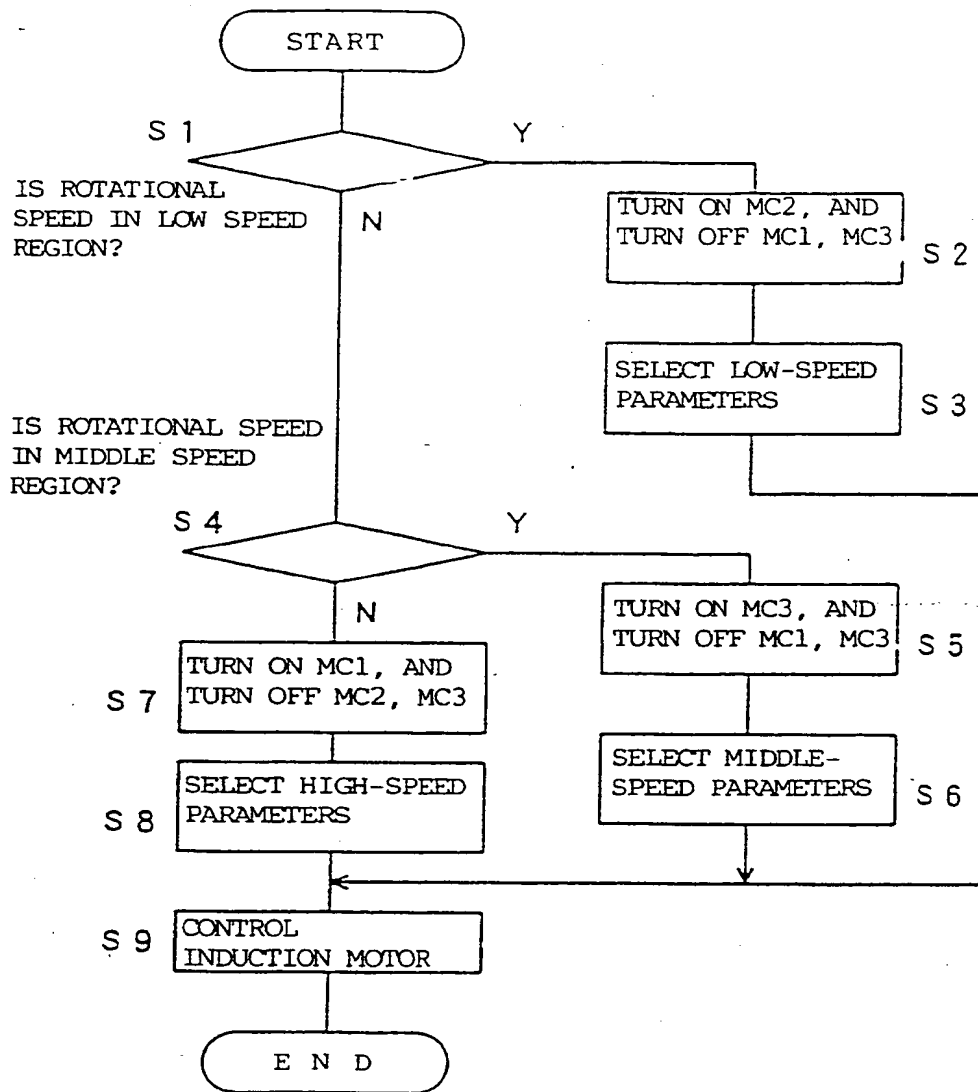
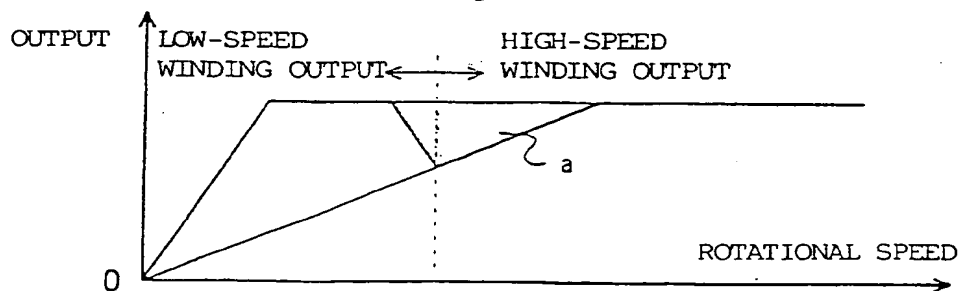


Fig. 4



# INTERNATIONAL SEARCH REPORT

International Application No PCT/JP92/00855

<b>I. CLASSIFICATION OF SUBJECT MATTER</b> (if several classification symbols apply, indicate all) <sup>6</sup>		
According to International Patent Classification (IPC) or to both National Classification and IPC		
Int. Cl <sup>5</sup> H02P7/36		
<b>II. FIELDS SEARCHED</b>		
Minimum Documentation Searched <sup>7</sup>		
Classification System	Classification Symbols	
IPC	H02P7/36	
Documentation Searched other than Minimum Documentation to the Extent that such Documents are Included in the Fields Searched <sup>8</sup>		
Jitsuyo Shinan Koho 1960 - 1991 Kokai Jitsuyo Shinan Koho 1971 - 1991		
<b>III. DOCUMENTS CONSIDERED TO BE RELEVANT <sup>9</sup></b>		
Category <sup>10</sup>	Citation of Document, <sup>11</sup> with indication, where appropriate, of the relevant passages <sup>12</sup>	Relevant to Claim No. <sup>13</sup>
Y	JP, A, 1-214293 (Fanuc Ltd.), August 28, 1989 (28. 08. 89), (Family: none)	1-5
Y	JP, A, 61-161991 (NTN Toyo Bearing Co., Ltd.), July 22, 1986 (22. 07. 86), (Family: none)	1-5
Y	JP, U, 56-171598 (Aichi-Emson Denki K.K.), December 18, 1981 (18. 12. 81), (Family: none)	1-5
<p><sup>10</sup> Special categories of cited documents:</p> <p>"A" document defining the general state of the art which is not considered to be of particular relevance</p> <p>"E" earlier document but published on or after the international filing date</p> <p>"L" document which may throw doubts on priority claim(s) or which is cited to establish the publication date of another citation or other special reason (as specified)</p> <p>"O" document referring to an oral disclosure, use, exhibition or other means</p> <p>"P" document published prior to the international filing date but later than the priority date claimed</p> <p>"T" later document published after the international filing date or priority date and not in conflict with the application but cited to understand the principle or theory underlying the invention</p> <p>"X" document of particular relevance; the claimed invention cannot be considered novel or cannot be considered to involve an inventive step</p> <p>"Y" document of particular relevance; the claimed invention cannot be considered to involve an inventive step when the document is combined with one or more other such documents, such combination being obvious to a person skilled in the art</p> <p>"Z" document member of the same patent family</p>		
<b>IV. CERTIFICATION</b>		
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September 7, 1992 (07. 09. 92)		September 29, 1992 (29. 09. 92)
International Searching Authority		Signature of Authorized Officer
Japanese Patent Office		

Form PCT/ISA/210 (second sheet) (January 1985)